Nm

SGR570 SERIES | PTO TORQUE TRANSDUCER

Accurate measurement of torque and speed

PTO Torque Transducer

Torqsense Digital rotary strain gauge series (SGR) Transducers use non contact technology eliminating the need for noisy slip rings. They are suitable for torque measuring, testing, feedback control of drive mechanisms and process control applications.

The SGR series transducers use modern strain gauge signal conditioning techniques to provide a high bandwidth low cost torque measuring solution with high overrange and overload capabilities.

FEATURES

- Transducers up to 2000Nm
- Large fully functional overrange capability of 250%
- Low linearity deviation of ± 0.05 % FSD
- Low hysteresis error of ± 0.05 % FSD
- Zero variation in torque signal with rotation (cyclic variation)
- Non contact signal transmission, no slip rings to wear out
- High digital sample rate of 4000 samples per second
- Adjustable torque data smoothness, low pass filter
- Speed measurement / Power computation
- High digital sample rate of 4000 samples per second
- Wide power supply range 12-32 VDC
- Compatible with ethernet gateway module

TECHNOLOGY

The SGR series torque transducers use a full four element strain gauge bridge to measure the torsion present on a shaft. The full bridge helps to diminish errors from any off-axis forces that are sometimes unintentionally applied to the transducer in some test setups. The full bridge also increases the sensitivity and the temperature performance of strain measurement.

A rotor mounted ultra-miniature microcontroller measures the strain gauge bridge and transfers the information back to the stator digitally eliminating any noise pickup usually associated with slip ring and other analog methods of transferring torque data from rotor to stator. External noise pickup into the gauge wiring is virtually eliminated due to the short distance between the strain gauge elements and the rotors measuring circuits.

A multipoint calibration method reduces any linearity errors within the sensor. A large functional overrange capability allows the peaks of a torque signal to be captured more faithfully without any clipping when operating the sensor close to its full scale rating.

All this combined with a mechanical overload capability of over 400% make the SGR series torque sensors a very robust and accurate torque measuring solution.

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PTO TRANSDUCERS OFFER:

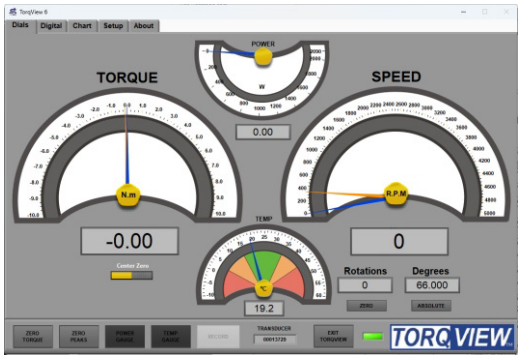
- Compatible with all PTO spline types
- Accurate measurement of torque and speed for testing equipment that use the PTO shafts.
- Power calculation
- Simple installation
- IP 65 for robust application where environmental issues may be a problem.
- Transducer configuration software to allow user to change transducer variables
- Connect straight to a PC for data viewing and logging
- Anti rotation eye hook, to stop transducer spinning around with the shaft.
- User configurable limits outputs.
- Wide range input voltage 11V - 32V
- Analog and digital outputs available
- Contactless measurement system (not slip ring)
- Temperature monitoring

SOFTWARE

TorqView is an easy to use advanced torque monitoring software, available to assist data recording and instrumentation displays that interface with Windows based PCs.

Features include: 3 types of display, text files compatible with Matlab and Excel and Real time chart plotting. See TorqView datasheet for more details.

LabView VI‘s are available for users to design their own process control applications. DLLs are also available for users to write their own custom software. Get data from across your network using the ethernet module.



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SPECIFICATION

Parameter	Condition	Data								Units
PTO Torque measurement system										
Measurement method		Full bridge strain gauge								
Torque range	*(Notes 1 & 2)*	Up to 2000Nm								Nm
Shaft type		Male 1 3/8" 6 spline to female 1 3/8" 6 spline ISO500-3 Type 1								
Specifications										
Combined non-linearity and hysteresis		± 0.1								%FS
Resolution		0.01								%FS
Repeatability		0.05								%FS
Basic Series Transducers ONLY										
Accuracy	20^0C, SM *(Note 4)*	± 0.2								%FS
3dB Bandwidth	*(Notes 5&6)*	250 (default ave. = 16)								Hz
Analog output										
Output voltages (Torque/Speed/Power)		Options available: ± 1 /± 5 /± 10 / Unipolar (SGR510 Series default setting is ±5Vdc) (SGR520 Series output voltages are user selectable)								Vdc
Load impedance		Maximum 1								KΩ
Output currents (Torque/Speed/Power)		Options available: 4-20 / 0-20 / 12±8 (SGR520 Series output currents are user selectable)								mA
4-20mA Loop resistance		Should not exceed 400								Ω
Advanced Series Transducers ONLY										
Accuracy	20^0C, SM *(Note 4)*	± 0.1								%FS
Digital averaging	*(Note 5)*	2	4	8	16	32	64	128	256	N
Noise Floor	20^0C, SM *(Note 4)*	0.06	0.04	0.03	0.02	0.015	0.01	0.01	0.01	%FS
3dB Bandwidth	*(Note 6)*	2000	1000	500	250	125	62	31	15	Hz
Digital output (Advanced Transducers ONLY)										
Connections		CAN Bus		Ethernet		RS232		USB		
Configuration		CAN 2.0B, 11bit Message Identifiers		IEEE 802.3 10BASE-T, 100BASE-TX		Data Bits: 8, Parity: None, Stop Bits:1		USB 2.0 Full-Speed		
Baud Rate(s)		1Mbps, 500Kbps, 250Kbps, 100Kbps		10Mbps, 100Mbps		115200bps, 38400bps, 9600bps		12 Mbps		
Output Rate	*(Note 7)*	Up to 4 kHz		Up to 1.9 kHz		Up to 1.1 kHz		Up to 4kHz		
Rotation speed/angle of rotation measurement system										
Measurement method		Opto switch through slotted disc								
Direct output signal		Pulse output direct from opto switch (TTL, 5V square wave)								
Accuracy		±1rpm up to 30,000rpm								
Rotational speed (max)	*(Note 3)*	30,000	20,000	15,000	12,000	9,000	6,000			RPM
Digital Processing Techniques Processing modes run simultaneously and can be applied to either analog channel or accessed individually via a digital connection.		**Processing Method**		**Update rate for analog and digital outputs**						
	Based on a standard 60-line grating. *(Note 11)*	Mode 1 (Slow Method) Frequency Count		1						Hz
		Mode 2 (Fast Method) Period Count		0 RPM	1					Hz
				> 0 RPM	$\frac{RPM}{\lceil \frac{RPM}{1000} \rceil}$					
Temperature										
Measurement method		Shaft mounted platinum temperature sensor								
Temperature accuracy		±1								^{0}C
Reference temperature T_{RT}		20								^{0}C
Compensated range, ΔT_O		0 to +90								^{0}C
Usable range, ΔT_S		-40 to +90								^{0}C
Temperature		Coefficient of zero 0.002								%
Temperature		Coefficient of span 0.01								%
Power supply										
Nominal voltage, V_S		11 to 32 (max)								V
Current consumption, I_S		250 (max) @ 12 VDC								mA
Power consumption, W_S		3								W
Allowed residual ripple of supply voltage, V_{ripple}		500 (above nominal supply voltage)								mVp-p
Electromagnetic compatibility										
EMC compatibility		EN 61326:2006								

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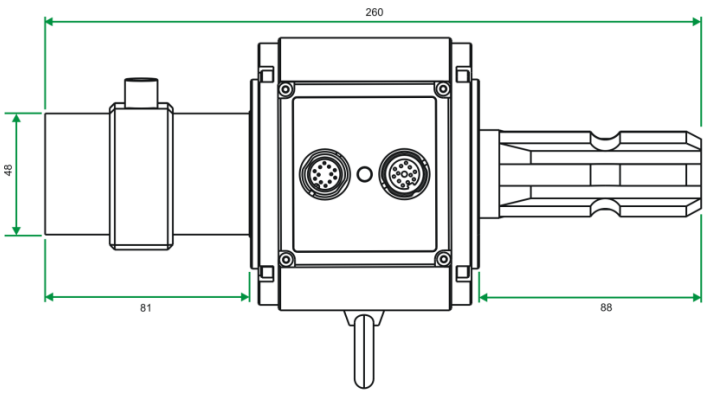
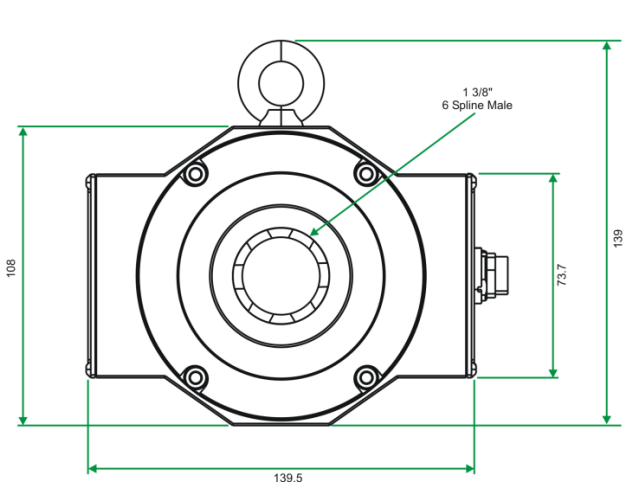
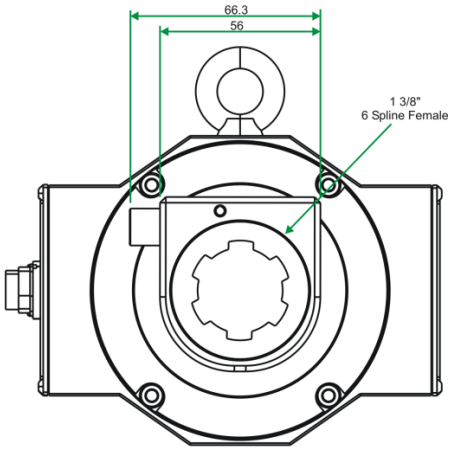
DIMENSIONS (0 - 2000NM) 6 SPLINE







Measurement units: Millimetres (mm)

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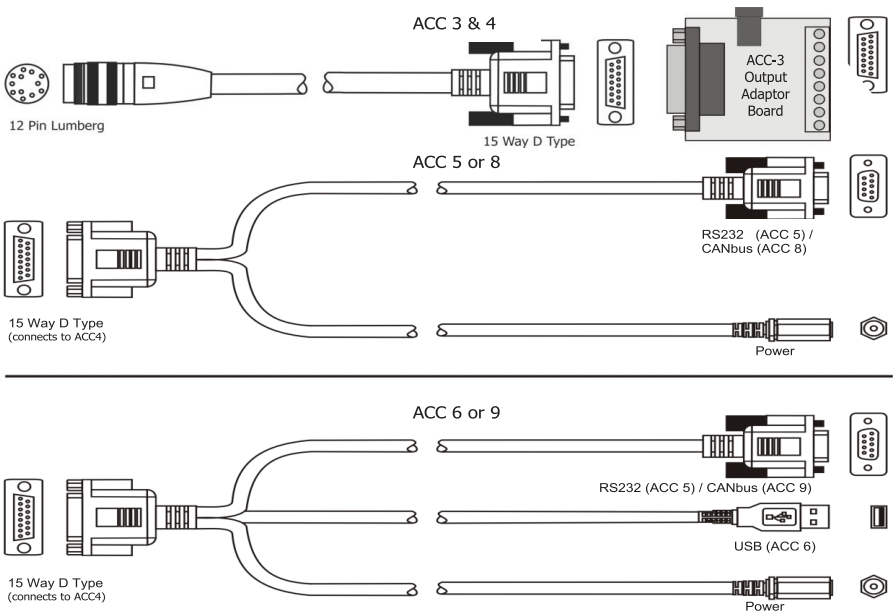
PTO TORQUE TRANSDUCERS – CONNECTOR AND LEAD OPTIONS

			Option Code	Remarks/Purpose
Connectors & Leads	**Basic**	**Advanced**		
Analog Connector *12 Pin Lumberg (female)*	◇	◇	ACC 1	*For user to self wire*
Digital Connector *12 Pin Lumberg (male)*		◇	ACC 2	*For user to self wire*
Analog Lead (Length 2.5m) *12 Pin Lumberg (female) to 15 way 'D' type connector (female)*	◇	◇	ACC 3	*For connecting SGR to user's system via 15 pin 'D' connector*
Digital Lead (Length 2.5m) *12 Pin Lumberg (male) to 15 way 'D' type connector (male)*		◇	ACC 4	*For connecting SGR to user's system via 15 pin 'D' connector*
Digital Lead Adapter (Length 1m) *15 Way 'D' type (female) to RS232 and Power Connectors*		◇	ACC 5	*For connecting SGR to PC via RS232* *[Also needs Digital Lead (ACC4) to connect to SGR]*
Digital Lead Adapter (Length 1m) *15 Way 'D' type (female) to RS232, USB and Power Connectors*		◇	ACC 6	*For connecting SGR to PC via USB (Option G) or RS232* *[Also needs Digital Lead (ACC4) to connect to SGR]*
Digital Lead Adapter (Length 1m) *15 Way 'D' type (female) to CANbus and Power Connectors*		◇	ACC 8	*For connecting SGR to PC via CANbus (Option H)* *[Also needs Digital Lead (ACC4) to connect to SGR]*
Digital Lead Adapter (Length 1m) *15 Way 'D' type (female) to CANbus, USB and Power Connectors*		◇	ACC 9	*For connecting SGR to PC via USB (Option G) or CANbus (Option H)* *[Also needs Digital Lead (ACC4) to connect to SGR]*

PTO SERIES TORQUE TRANSDUCERS – ADDITIONAL RELATED PRODUCTS

	Code	Remarks/Purpose
Transducer Display ETD	ETD	*Display readout*
AC Mains Adapter Power Supply	PSU 1	*For providing 12-32Vdc*
Transducer Signal Breakout Unit	SBU 1	
TorqView	TV	*Torque Monitoring Software*



Data parameters measured at +20°C
Sensor Technology Ltd reserves the right to change specification and dimensions without notice.

GLOSSARY OF TERMS AND DEFINITIONS USED IN THIS DATASHEET

• **Accuracy –** The degree of conformity of a measured or calculated quantity, which will show the same or similar results. Accuracy of the overall TorqSense system is limited by the combined error of several factors such as linearity, hysteresis, temperature drifts and other parameters affecting measurements. If errors in the system are known or can be estimated, an overall error or uncertainty of measurement can be calculated.

• **Digital averaging –** The application of algorithms to reduce white noise. In any electronic system, electronic white noise is mixed with the signal and this noise usually limits the accuracy. To reduce the influence of white noise and increase the accuracy of the system different averaging algorithms can be applied. In the TorqSense system a flying digital averaging technique is applied to reduce the white noise commensurate with the level of accuracy required. However, as any averaging algorithm works as a low pass filter, the more averaging that is applied the lower the frequency response. Therefore, each Torqsense system should be optimised to the customer's requirements by choosing the right combination of accuracy/frequency response. Please see relevant part of the Datasheet and User Manual.

Note 1: Any torque/FSD is possible between ranges – please specify max rated torque.

Note 2: Max rated torque should not be exceeded.

Note 3: Please consult factory for applications requiring rotational speeds that exceed maximum figures given. Transducers fitted for IP65 will have running speeds considerably reduced, increased drag torque and accuracy can be affected.

Note 4: SM – Static Mode. Dynamic values will depend upon user application and has to be adjusted accordingly.

Note 5: Digital averaging can be configured by user to optimise accuracy/frequency response for specific user applications. Digital averaging default setting is N=16. For details see User Manual.

Note 6: >5Khz Sample Rate. Up to 10Khz sample rate possible, please consult factory. Digital averaging also affects the analog output, max analog output 3dB Bandwidth = 5Khz when digital average is 1.

Note 7: Output rate figures are calculated from the time taken to capture 10000 torque readings. Testing was conducted with each connection method configured at its maximum baud rate. The maximum output rate available for CAN and USB is dependant on the transducers setup. USB - USB is a host based bus architecture, because of this the output rate achievable will be affected by other bus traffic and host activity. USB has two transfer modes, Single Transfer which requests 1 reading at a time and Bulk Transfer which transfers readings in blocks of 50 Torque/Speed pairs. CAN Bus - to achieve a Torque reading output rate of 10KHz, the Speed reading output rate must be reduced to 100Hz.

Note 8: 2 x analog channels available. Default settings are Channel 1 (voltage/current) – torque. Channel 2 (voltage/current) – speed or power, if ordered.

Note 9: At very high speeds, for better balance the factory recommend plain or splined shafts.

Note 10: Transducers fitted for IP65 will have running speeds considerably reduced, increased drag torque and accuracy can be affected.

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